

# On Monotonic Solutions of Nonlinear Quadratic Integral Equation of Convolution Type

## Author's Details:

Wagdy G. El-Sayed<sup>1</sup>, Mahmoud M. El-Borai<sup>2</sup>, Mohamed M.A. Metwali<sup>3</sup>,  
 Nagwa I. Shemais<sup>4,2</sup> Department of mathematics and computer science, Faculty of Science, Alexandria  
 University, Alexandria, Egypt <sup>3,4</sup> Department of mathematics, Faculty of Science , Damanhour University,  
 Damanhour, Egypt  
<sup>1</sup>wagdygoma@alexu.edu.eg, <sup>2</sup>m m elborai@yahoo.com,  
<sup>3</sup>m.metwali@yahoo.com, <sup>4</sup>n.ibrahim90@yahoo.com

## Abstract:

Using the technique of a suitable measure of non-compactness and the Darbo fixed point, we investigate the existence of nondecreasing solutions for a quadratic nonlinear -integral equation of convolution type. Our investigations take place in  $C(\mathbb{R}_+)$ , the Banach space of real and continuous functions defined on  $\mathbb{R}_+$ ,  $\mathbb{R}_+ := [0, \infty)$ . An example is also discussed to indicate the natural realizations of our abstract result.

**Keywords:** Quadratic integral equation, measure of noncompactness, existence and uniqueness, Darbo's fixed point theorem.

## 1. Introduction.

It is well known that several problems in many branches in real world such as in physics, engineering,...ect, can be modeled as Quadratic integral equations see for example([4], [6], [7], [17]), and the references therein, which are often applicable in the kinetic theory of gases, in the traffic theory, and in the radiative transfer. Especially the so called quadratic integral equation of Chandrasekhar type can be seen in many application (cf.([9],[10],[30],[12],[29])).

In [33], the authors studied the nondecreasing solutions of a Quadratic integral equation of Urysohn type

$$x(t) = a(t) + f\left(t, x(t)\right) \int_0^1 u(t, s, x(s)) ds, t \in I = [0, 1].$$

the authors in [18] studied the existence of integral solutions of the following integral equation

$$x(t) = f_1\left(t, \int_0^t k(t, s) f_2(s, x(s)) ds\right).$$

In [19], the authors studied the existence of solutions for the perturbed functional integral equations of convolution type

$$x(t) = f_1(t, x(t)) + f_2\left(t, \int_0^\infty k(t-s) Q(x)(s) ds\right), t \in \mathbb{R}_+$$

the space  $L^p(\mathbb{R}_+)$  in (the space of Lebesgue integrable functions on  $\mathbb{R}_+$ ).

In [1], the authors studied the solvability of the following nonlinear quadratic integral equation

$$x(t) = g(t) + (Tx)(t) \int_0^t k(t, s) f(s, x(\varphi(s))) ds, t \in [0, M].$$

## 2. Notation And Auxiliary Results.

We need to recall some basic concepts that will need later. Let  $E$  be an infinite dimensional Banach space with norm  $\|\cdot\|$  and zero element  $\theta$ . Denote by  $B_r = B(\theta, r)$  the closed ball centered at  $\theta$  and with radius  $r$ . If  $X$  is nonempty and subset of  $E$ , we denote the symbols  $\bar{X}$  and  $\text{Conv}X$  stand for the closure and closed

convex hull of  $X$ , respectively. Moreover, we use the standard notation  $X + Y$  and  $\lambda X$  for algebraic operations on sets.

Further on, we denote by  $M_E$  the family of all nonempty and bounded subsets of  $E$  and  $N_E$  the family of all nonempty relatively compact sets.

**Definition 2.1.** (Measure of noncompactness)[11]

A mapping  $\mu : M_E \rightarrow [0, \infty)$  is said to be a measure of noncompactness in  $E$  if it satisfies the following conditions,

1<sup>o</sup> the family  $\ker \mu = \{X \in M_E : \mu(X) = 0\}$  is nonempty and  $\ker \mu \subset N_E$ , where  $\ker \mu$  is called the kernel of the measure  $\mu$ .

2<sup>o</sup>  $X \subset Y \Rightarrow \mu(X) \leq \mu(Y)$ ,

3<sup>o</sup>  $\mu(\text{Conv} X) = \mu(X) = \mu(\bar{X})$ ,

4<sup>o</sup>  $\mu[\lambda X + (1 - \lambda)Y] \leq \lambda \mu(X) + (1 - \lambda)\mu(Y), \lambda \in [0, 1]$ ,

5<sup>o</sup> If  $X_n \in M_E, X_n = \bar{X}_n$  and  $X_{n+1} \subset X_n$  for  $n = 1, 2, \dots$  and if

$$\lim_{n \rightarrow \infty} \mu(X_n) = 0, \text{ then the set } X_\infty = \bigcap_{n=1}^{\infty} X_n \neq \varnothing (\text{nonempty and compact}).$$

The family  $\ker \mu$  described above is called the kernel of the measure of noncompactness  $\mu$ . For further details concerning of measures of noncompactness and its properties, we refer to [11]. In what follows we will work in the Banach space  $C(\mathbb{R}_+)$  consisting of all real functions defined and continuous on  $\mathbb{R}_+ = [0, \infty)$ .

The space  $C(\mathbb{R}_+)$  is equipped with the standard norm  $\|x\| = \max\{|x(t)| : t \in \mathbb{R}_+\}$ . Now, let us recall the definition of a measure of noncompactness in  $C(\mathbb{R}_+)$  which will be used in our investigations. This measure was introduced in [14]. Let us fix a nonempty and bounded subset  $X$  of  $C(\mathbb{R}_+)$ . For  $x \in X$  and  $\varepsilon > 0$ , we let

$$w(x, \varepsilon) = \sup\{|x(t) - x(s)| : t, s \in \mathbb{R}_+, |t - s| \leq \varepsilon\},$$

$$w(X, \varepsilon) = \sup\{w(x, \varepsilon) : x \in X\},$$

And

$$w_0(X) = \lim_{\varepsilon \rightarrow 0} w(X, \varepsilon).$$

Also, let us define the following quantities,

$$d(x) = \sup\{|x(s) - x(t)| - [x(s) - x(t)] : t, s \in \mathbb{R}_+, t \sim s\},$$

$$d(X) = \sup\{d(x) : x \in X\}.$$

Notice that  $d(X) = 0$  if and only if all functions belonging to  $X$  are nondecreasing on  $\mathbb{R}_+$ . It can be proved in [14], that the function  $\mu : M_{C(\mathbb{R}_+)} \rightarrow \mathbb{R}$  given by

$$\mu(X) = w_0(X) + d(X),$$

is a measure of noncompactness on  $C(\mathbb{R}_+)$ . The kernel  $\ker \mu$  of this measure contains nonempty and bounded sets  $X$  such that functions from  $X$  are equicontinuous and nondecreasing on  $\mathbb{R}_+$ .

In the end of this section, we recall the fixed point of Darbo which enables us to prove the solvability of several integral equations considered in nonlinear analysis. To quote this theorem we need the following definitions.

**Definition 2.2.** [11] The function  $f : I \times \mathbb{R} \rightarrow \mathbb{R}$  satisfies Caratheodory condition if it satisfies the following two conditions:

- (1)  $f$  is measurable in  $t \in I$  for any  $x \in \mathbb{R}$ .

(2)  $f$  is continuous in  $x \in \square$  for almost all  $t \in I$ .

**Definition2.3.** (Darbo condition) [15]

Let  $\Omega$  be a nonempty subset of a Banach space  $E$  and let  $A: \Omega \rightarrow E$  be a continuous operator which transforms bounded sets onto bounded ones. We say that  $A$  satisfies the Darbo condition (with a constant  $k \geq 0$ ) with respect to a measure of noncompactness  $\mu$  if for any bounded subset  $X$  of  $\Omega$ , we have  $\mu(AX) \leq k\mu(X)$ .

Note that, if  $A$  satisfies the Darbo condition with  $k < 1$ , then it is called a contraction operator with respect to  $\mu$ .

**Theorem2.1.** (Darbo fixed point theorem) [5]

Let  $\Omega$  be a nonempty, bounded, closed and convex subset of  $E$  and let  $f: \Omega \rightarrow \Omega$  be a continuous transformation which is a contraction with respect to the measure of noncompactness  $\mu$ , i.e. there exists a constant  $k \in [0, 1)$  such that

$$\mu(fX) \leq k\mu(X),$$

for any nonempty subset  $X$  of  $\mu$ . Then  $f$  has at least one fixed point in the set  $\mu$ .

**Remark2.1.** Under the assumptions of the above theorem, it can be shown that the set  $\text{fix } F$  of fixed points of  $F$  belonging to  $\mu$  is a member of the family  $\ker \mu$  (cf., [11]). This fact permits us to characterize solutions of considered operator equations.

**3. Main result**

In this section, we will study the nonlinear quadratic integral equation of convolution type having the form,

$$x(t) = g(t) + h(t, x(t)) \int_0^\infty k(t-s) f(s, x(s)) ds, t \in \square_+. \quad (1)$$

All functions appearing in equation (1) are known while  $x = x(t)$  is an unknown function. For further purposes let us also recall that the function  $h = h(t, x)$  involved in (1) generates the operator  $H$  defined by the formula,

$$(Hx)(t) = h(t, x(t)), \quad (2)$$

where  $x = x(t)$  is an arbitrary function defined on  $\square$ . Such an operator is called the superposition operator and have several interesting properties([11]). In what follows, we will investigate the integral equation (1) assuming the following conditions are satisfied.

- (i)  $g \in C(\square_+)$  is continuous nondecreasing and nonnegative.
- (ii)  $h: \square_+ \times \square \rightarrow \square$  is continuous function such that there exists a constant  $a \geq 0$  such that  $|h(t, x) - h(t, y)| \leq a|x - y|$  for all  $t \in \square_+$  and  $x, y \in \square$ . Moreover,  $h: \square_+ \times \square_+ \rightarrow \square_+$ .
- (iii)  $d(Hx) \leq ad(x)$  for any nonnegative function  $x \in C(\square_+)$ , where  $H$  is the superposition operator defined in (2).
- (iv)  $k: \square_+ \rightarrow \square$  is continuous and nondecreasing where

$$K = \sup \left\{ \int_0^\infty k(t-s) ds : t, s \in \square_+ \right\}.$$

- (v)  $f: \square_+ \times \square \rightarrow \square$  is continuous function and nondecreasing such that there exists a nondecreasing function  $m: \square_+ \rightarrow \square_+$ , such that  $|f(s, x)| \leq m(|x|)$  for all  $s \in \square_+$  and  $x \in \square$ .
- (vi) There exist  $r_0 > 0$  with

$$\|g\| + (ar_0 + b)Km(r_0) \leq r_0,$$

such that  $aKm(r_0) < 1$ , where  $b = \max\{h(t, 0) : t \in \square_+\}$ .

Now we are in position to present our main result.

**Theorem 3.1.** Under the assumptions (i)-(vi), equation (3.1) has at least one solution  $x = x(t)$  which belong the space  $C(\square_+)$  and nondecreasing.

Proof: Let us consider the operator  $U$  defined on the space  $C(\square_+)$  in the following way,

$$(Ux)(t) = g(t) + h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, x(\tau)) d\tau,$$

taking into account assumptions (i), (ii), (iv) and the properties of the superposition operator, we infer that the function  $Ux$  is continuous on  $\square_+$  for any function  $x \in C$  (the operator  $U$  transforms the space  $C(\square_+)$  into itself).

$$\begin{aligned} |(Ux)(t)| &\leq |g(t)| + |h(t, x(t))| \int_0^\infty |k(t-\tau)| |f(\tau, x(\tau))| d\tau \\ &\leq |g(t)| + [|h(t, x(t)) - h(t, 0)| + |h(t, 0)|] \int_0^\infty |k(t-\tau)| m(|x(\tau)|) d\tau \\ &\leq |g(t)| + (a|x(t)| + |h(t, 0)|) \int_0^\infty |k(t-\tau)| m(|x(\tau)|) d\tau \\ &\leq |g(t)| + (a|x(t)| + h(t, 0)) m(\|x\|) \int_0^\infty |k(t-\tau)| d\tau \\ &\leq |g(t)| + (a|x(t)| + h(t, 0)) m(\|x\|) K. \end{aligned}$$

The above inequality yields

$$\|Ux\| \leq \|g\| + (a\|x\| + b) Km(\|x\|),$$

where  $b = \max\{h(t, 0) : t \in \square_+\}$ .

Hence, keeping in mind assumption (vi), we deduce that there exists  $r_0 > 0$  and such that the operator  $U$  on the subset  $B_{r_0}^+$  of the ball  $B_{r_0}$  defined as follows,

$$B_{r_0}^+ = \{x \in B_{r_0} : x(t) > 0\}.$$

Obviously, the set  $B_{r_0}^+$  is nonempty, bounded, closed, and convex. Hence in view of our assumptions we infer that  $U$  transforms the ball  $B_{r_0}^+$  into itself. Then, we show that  $U$  is continuous on the set  $B_{r_0}^+$ . To do this, let us fix  $\varepsilon \geq 0$  and take arbitrarily  $x, y \in B_{r_0}^+$  such that  $\|x - y\| \leq \varepsilon$ , then we have for  $t \in \square_+$ ,

$$\begin{aligned} |(Ux)(t) - (Uy)(t)| &= \left| h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, x(\tau)) d\tau - h(t, y(t)) \int_0^\infty k(t-\tau) f(\tau, y(\tau)) d\tau \right| \\ &\leq \left| h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, x(\tau)) d\tau - h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, y(\tau)) d\tau \right| \\ &\quad + \left| h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, y(\tau)) d\tau - h(t, y(t)) \int_0^\infty k(t-\tau) f(\tau, y(\tau)) d\tau \right| \\ &\leq [|h(t, x(t)) - h(t, 0)| + |h(t, 0)|] \int_0^\infty k(t-\tau) |f(\tau, x(\tau)) - f(\tau, y(\tau))| d\tau \\ &\quad + |h(t, x(t)) - h(t, y(t))| \int_0^\infty |k(t-\tau) f(\tau, y(\tau))| d\tau \\ &\leq (a|x(t)| + b) \int_0^\infty k(t-\tau) |f(\tau, x(\tau)) - f(\tau, y(\tau))| d\tau + a|x(t) - y(t)| \end{aligned}$$

$$\begin{aligned} & \times \int_0^\infty |k(t-\tau)| m(|y(\tau)|) d\tau \\ & \leq (ar_0 + b)K\beta_0(\varepsilon) + a\varepsilon Km(r_0), \end{aligned}$$

where we denoted

$$\beta_0(\varepsilon) = \sup \{ |f(\tau, x(\tau)) - f(\tau, y(\tau))| : \tau \in \mathbb{R}_+, x, y \in [0, r_0], |x - y| \leq \varepsilon \}.$$

Observe that  $\beta_0(\varepsilon) \rightarrow 0$  as  $\varepsilon \rightarrow 0$  which is a consequence of the uniform continuity of the function  $f$  on the set  $\mathbb{R}_+ \times [0, r_0]$ . Next, we get

$$\|Ux - Uy\| \leq (ar_0 + b)K\beta_0(\varepsilon) + a\varepsilon Km(r_0),$$

which yields the continuity of the operator  $U$  on the set  $B_{r_0}^+$ . Now, let us take a nonempty set  $x, X \in B_{r_0}^+$ .

Further fix arbitrary  $\varepsilon > 0$  and choose  $x \in X$  and  $t, s \in \mathbb{R}_+$ , such that  $|x - y| \leq \varepsilon$ . Then, taking into account our assumption, we obtain

$$\begin{aligned} & |(Ux)(s) - (Ux)(t)| \leq |g(s) - g(t)| \\ & + \left| h(s, x(s)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau - h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, x(\tau)) d\tau \right| \\ & \leq w(g, \varepsilon) + \left| h(s, x(s)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau - h(t, x(t)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau \right| \\ & \quad + \left| h(t, x(t)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau - h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, x(\tau)) d\tau \right| \\ & \leq w(g, \varepsilon) + |h(s, x(s)) - h(t, x(t))| \int_0^\infty k(s-\tau) |f(\tau, x(\tau))| d\tau \\ & \quad + |h(t, x(t))| \int_0^\infty |k(s-\tau)k(t-\tau)| |f(\tau, x(\tau))| d\tau \\ & \leq w(g, \varepsilon) + [|h(s, x(s)) - h(t, x(s))| + |h(t, x(s)) - h(t, x(t))|] \\ & \quad \times \int_0^\infty k(s-\tau) m(|x(\tau)|) d\tau \\ & \quad + [|h(t, x(t)) - h(t, 0)| + |h(t, 0)|] \int_0^\infty |k(s-\tau) - k(t-\tau)| m(|x(\tau)|) d\tau \\ & \leq w(g, \varepsilon) + [w_0(h, \varepsilon) + a|x(s) - x(t)|] m(\|x\|) \\ & \quad \times \int_0^\infty |k(s-\tau)| d\tau + (a\|x\| + b)m(\|x\|) \int_0^\infty |k(s-\tau) - k(t-\tau)| d\tau \\ & \leq w(g, \varepsilon) + [w_0(h, \varepsilon) + aw(x, \varepsilon)] Km(r_0), \end{aligned}$$

where we have denoted

$$w_0(h, \varepsilon) = \sup \{ |h(t, x) - h(s, x)| : t, s \in \mathbb{R}_+, |t - s| \leq \varepsilon, x \in [0, r_0] \}.$$

Notes that in view of the uniform continuity of the function  $h$  on the set  $\mathbb{R}_+ \times [0, r_0]$ , we have that

$w_0(h, \varepsilon) \rightarrow 0$  as  $\varepsilon \rightarrow 0$ . This fact with the above estimate allow us to have,

$$w_0(UX) \leq aKm(r_0)w_0(X). \tag{3}$$

Further, fix arbitrary  $x \in X$  and  $t, s \in \mathbb{R}_+$  with  $t \leq s$ . Then using the assumptions in our theorem, we get

$$\begin{aligned} & |(Ux)(s) - (Ux)(t)| - [(Ux)(s) - (Ux)(t)] \\ & = \left| g(s) - g(t) + h(s, x(s)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau - h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, x(\tau)) d\tau \right| \\ & - [g(s) - g(t) + h(s, x(s)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau \\ & - h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, x(\tau)) d\tau] \\ & \leq \{ |g(s) - g(t)| - [g(s) - g(t)] \} \\ & = \left| h(s, x(s)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau - h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, x(\tau)) d\tau \right| \end{aligned}$$

$$\begin{aligned}
 & -[h(s, x(s)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau - h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, x(\tau)) d\tau] \\
 & \leq \left| h(s, x(s)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau - h(t, x(t)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau \right| \\
 & + \left| h(t, x(t)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau - h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, x(\tau)) d\tau \right| \\
 & -[h(s, x(s)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau - h(t, x(t)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau] \\
 & -[h(t, x(t)) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau - h(t, x(t)) \int_0^\infty k(t-\tau) f(\tau, x(\tau)) d\tau] \\
 & \leq |h(s, x(s)) - h(t, x(t))| \int_0^\infty |k(s-\tau)| m(|x(\tau)|) d\tau \\
 & + |h(t, x(t))| \int_0^\infty |k(s-\tau) - k(t-\tau)| m(|x(\tau)|) d\tau \\
 & -[h(s, x(s)) - h(t, x(t))] \int_0^\infty k(s-\tau) |f(\tau, x(\tau))| d\tau \\
 & -h(t, x(t)) \int_0^\infty [k(s-\tau) - k(t-\tau)] f(\tau, x(\tau)) d\tau \\
 & \leq (|h(s, x(s)) - h(t, x(t))| - [h(s, x(s)) - h(t, x(t))]) \\
 & \times \int_0^\infty k(s-\tau) |f(\tau, x(\tau))| d\tau \\
 & \leq d(Hx) \int_0^\infty k(s-\tau) f(\tau, x(\tau)) d\tau \\
 & \leq d(Hx) K m(r_0) \leq a K m(r_0) d(x).
 \end{aligned}$$

Then, we have

$$d(UX) \leq aK m(r_0) d(X). \tag{4}$$

Now from equation (3), (4), and the definition of measure of noncompactness given in section 2, we get

$$\mu(UX) \leq aK m(r_0) \mu(X).$$

Hence, taking into account that  $aK m(r_0) < 1$  and the theorem 2.1 we obtain that the integral equation (1) has at least one solution in  $C(\square_+)$ . Moreover, in view of Remark 2.1 and the description of the kernel of a measure of noncompactness  $\mu$ , we deduce that all solutions of the integral equation (1) belonging to the set  $B_{r_0}^+$  are nondecreasing on  $\square_+$ . This complete the proof.

**Corollary 3.1.** Observe that assuming that  $g(t) > 0$ , for  $t \in \square_+$ , we infer that all solutions of the integral equation (1) belonging to the set  $B_{r_0}^+$  are continuous, nondecreasing, and positive on  $\square_+$ .

**proof**

In the case when the assumptions of theorem are satisfied, then the operator  $U$  has a fixed point say  $X$  i.e

$$UX = X,$$

then

$$\mu(X) = \mu(UX) \leq aK m(r_0) \mu(X),$$

hence

$$(1 - aK m(r_0)) \mu(X) \leq 0.$$

Since  $aK m(r_0) < 1$  then

$$0 < (1 - aK m(r_0)) < 1,$$

then

$$\mu(X) = 0.$$

So

$$\omega(X) + d(X) = 0,$$

then  $\omega(X) = d(X) = 0$ , then the solutions of the integral equation (1) will be monotonic nondecreasing. We will study the uniqueness of solution for equation (1).

#### 4. Existence of a unique solution

**Theorem 4.1.** Let the assumptions of the above Theorem be satisfied but the assumptions (v)(vi), will be replaced by the following assumptions

(a)  $f: \mathbb{R}_+ \times \mathbb{R}_+ \rightarrow \mathbb{R}$  Satisfies lipschitz condition in  $x$  with constant  $l \geq 0$ , such that

$$|f(t, x(t)) - f(t, y(t))| \leq l|x - y|,$$

also assume that  $|f(t, x(t))| \leq l_1|x|, l_1$  is positive constant

$$(b) (ar_0 + b)Kl + aKl_1r_0 < 1.$$

**Proof:**

From assumption (ii), we have

$$|h(t, x(t))| \leq |h(t, x(t)) - h(t, 0)| + |h(t, 0)| \leq a|x| + b \Rightarrow |h(t, x(t))| \leq a|x| + b,$$

for the uniqueness of solution of equation(3.1), let  $x(t), y(t)$  be any two solutions for the equation (1), in  $B_{r_0}$ , we have

$$\begin{aligned} \|x - y\|_{C(\mathbb{R}_+)} &= |h(t, x(t)) \int_0^\infty k(t - \tau)f(\tau, x(\tau))d\tau - h(t, y(t)) \int_0^\infty k(t - \tau)f(\tau, y(\tau))d\tau| \\ &\leq |h(t, x(t)) \int_0^\infty k(t - \tau)f(\tau, x(\tau))d\tau - h(t, x(t)) \int_0^\infty k(t - \tau)f(\tau, y(\tau))d\tau| + |h(t, x(t)) \int_0^\infty k(t - \tau)f(\tau, y(\tau))d\tau - h(t, y(t)) \int_0^\infty k(t - \tau)f(\tau, y(\tau))d\tau| \\ &\leq [|h(t, x(t)) - h(t, 0)| + |h(t, 0)|] + |h(t, x(t)) - h(t, y(t))| \int_0^\infty |k(t - \tau)f(\tau, y(\tau))|d\tau \\ &\leq (a|x(t)| + b) \int_0^\infty k(t - \tau)|f(\tau, x(\tau)) - f(\tau, y(\tau))|d\tau + a|x(t) - y(t)| \times \int_0^\infty |k(t - \tau)m(|y(\tau)|)|d\tau \\ &\leq (a|x(t)| + b)Kl|x(t) - y(t)| + aKl_1|x(t)||x(t) - y(t)| \\ &\leq ((a|x(t)| + b)Kl + aKl_1|x(t)|)|x(t) - y(t)| \\ &\leq ((a\|x\| + b)Kl + aKl_1\|x\|)\|x - y\|_{C(\mathbb{R}_+)}. \end{aligned}$$

Therefore we have.

$$(1 - (a\|x\| + b)Kl + aKl_1\|x\|)\|x - y\|_{C(\mathbb{R}_+)} \leq 0.$$

$$(1 - (ar_0 + b)Kl + aKl_1r_0)\|x - y\|_{C(\mathbb{R}_+)} \leq 0,$$

which implies that  $\|x - y\|_{C(\mathbb{R}_+)} \leq 0$ , thus we have  $\|x - y\|_{C(\mathbb{R}_+)} \rightarrow 0, \Rightarrow x = y$  this complete the proof.

In the following we will present an example to ensure the assumptions of our existence theorem.

#### 5. Example

Consider the following quadratic integral equation,

$$x(t) = te^{-t} + \frac{1}{4} x(t) \int_0^\infty -(t - s)e^{-(t-s)^2} \arctan\left(\frac{x^2(s)}{1+s^2}\right) ds, \quad t \geq 0 \tag{5}$$

in our example we have  $g(t) = te^{-t}, h(t, x(t)) = \frac{1}{4} x$ , further notes that  $k(t - s) = -(t - s)e^{-(t-s)^2}$  and  $f(s, x) = \arctan\left(\frac{x^2}{1+s^2}\right)$ .

first of all observe that  $g(t)$  satisfies assumption (i) with norm  $\|x\| = \frac{1}{e}$ .

Further notes that the function  $h(t, x)$  satisfies assumption (ii) with  $a = \frac{1}{4}$  since  $h: \mathbb{R}_+ \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$  and

$$|h(t, x) - h(t, y)| = \frac{1}{4} |x - y|,$$

for  $x, y \in \mathbb{R}$  and  $t \in \mathbb{R}_+$ . It is easy to show that this function satisfies assumption (iii), indeed, taking an arbitrary nonnegative function  $x \in C(\mathbb{R}_+)$  and  $t, s \geq 0$  such that  $t \geq s$ , we obtain

$$\begin{aligned} |(Hx)(s) - hx(t)| - [(Hx)(s) - hx(t)] &= |h(s, x(s)) - h(t, x(t))| - [h(s, x(s)) - h(t, x(t))] \\ &= \left| \frac{1}{4}x(s) - \frac{1}{4}x(t) \right| - \left[ \frac{1}{4}x(s) - \frac{1}{4}x(t) \right] \\ &= \frac{1}{4} \left( \left| \frac{1}{4}x(s) - \frac{1}{4}x(t) \right| - \left[ \frac{1}{4}x(s) - \frac{1}{4}x(t) \right] \right) \leq \frac{1}{4}d(x). \end{aligned}$$

Hence, we have

$$d(Hx) \leq ad(x)$$

From assumption (iv) we have  $K = \frac{1}{2}$ .

Indeed

$$\int_0^\infty -(t-s)e^{-(t-s)^2} ds = \frac{-1}{2} e^{-(t-s)^2} \Big|_0^\infty = \frac{1}{2} e^{-t^2},$$

thus,  $K = \frac{1}{2}$ . Next, we note that the function  $f(s, x)$  satisfies assumption (v). Moreover, we have

$$|f(s, x)| \leq x^2,$$

so the function  $m(x) = x^2$ .

Now, let us consider the inequality from the assumption (vi), which has the form

$$\begin{aligned} \|g\| + (ar_0 + b)Km(r_0) &\leq r_0, \\ \frac{1}{e} + \left(\frac{1}{4}r_0\right)^{\frac{1}{4}}r_0^2 &\leq r_0 \end{aligned} \tag{6}$$

Using the standard methods of differential calculus we can verify that the function  $y(r_0) = r_0 - \frac{1}{8}r_0^3$  attains its maximum at the point  $r_0 = 2\sqrt{\frac{2}{3}}$ , and  $y(r_0) = \frac{4}{3}\sqrt{\frac{2}{3}} \geq \frac{1}{e}$ . So the number  $r_0$  is a positive solution of the inequality(6). finally taking in account all above established facts and the Theorem (3.1) we conclude that the above example has at least one solution defined, continuous and nondecreasing on  $\mathbb{R}_+$ .

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